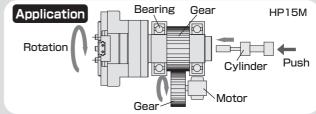
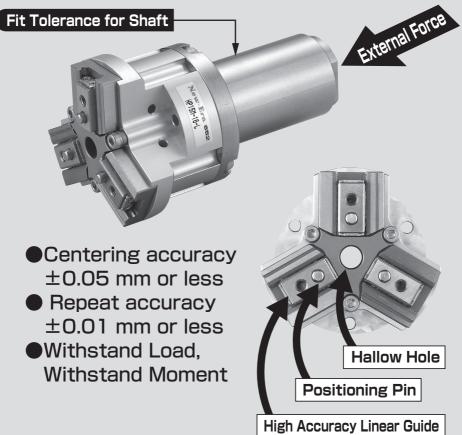
Parallel 3-Finger Mechanical Gripper

HP15M_{Series}

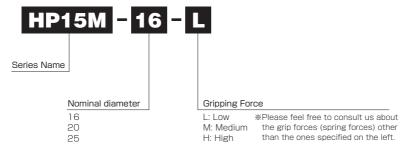
- Mechanical Gripper (Gripping by the use of the spring force)
- High rigidity and high accuracy realized by the use of the linear guide
- Gripping at the long point is available.
- With a hollow hole



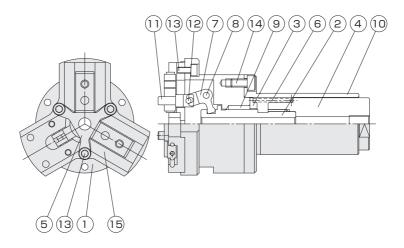


HP15M Series

Model Code No.



■ Internal Structure Diagram



Parts List

NO	Name	Material	NO	Name	Material
1	Main Body	Aluminum Alloy	9	Metal	Oil-impregnated Sintered Bearing
2	Piston Rod	Stainless Steel	10	Case	Stainless Steel
3	Pressure Cover	Aluminum Alloy	11	Knuckle	Stainless Steel
4	Pressure Cover	Stainless Steel	12	Roller	Carbon Steel
5	Pressure Cover	Stainless Steel	13	Hexagon Socket Head Bolt	Stainless Steel
6	Spring	Spring Steel	14	Hexagon Socket Head Bolt	Stainless Steel
7	Action Lever	Carbon Steel	15	Bearing	Stainless Steel
8	Fulcrum Pin	Carbon Tool Steel			

■ Specifications

Elastic Body to be Used		Compression spring		
Action Type		Single Acting Normally Close (External force drive at opening)		
Operating Temperature	[°C]	0~120		
Lubrication		Required		
Maximum Operating Cycle	[Cycle/min]	180		
Centering Accuracy	[mm]	±0.07		
Repeat Accuracy [mm]		±0.01		
Applicable Switch		Not mountable		

Action Type	Model	Nominal diameter [mm]	Opening/ Closing Stroke [mm] Note)3	Gripping Force (At Closing) [N]	Extrusion Force [N]	Allowable Extrusion Force [N]	Product Mass [g]	Note)2 Lever Ratio
	HP15M-16-L			3	14	50	300	1:1.1
	HP15M-16-M	16 3 (3~4.8	3 (3~4.8)	5	24			
	HP15M-16-H			7	34			
Single	HP15M-20-L			7	38	130	560	1:1.1
Acting Normally	HP15M-20-M	20	5 (5~7)	12	64			
Close	HP15M-20-H			17	88			
	HP15M-25-L	25	7 (6.3~8.8)	12	66	210	870	1:1.1
	HP15M-25-M			18	95			
	HP15M-25-H			26	138			

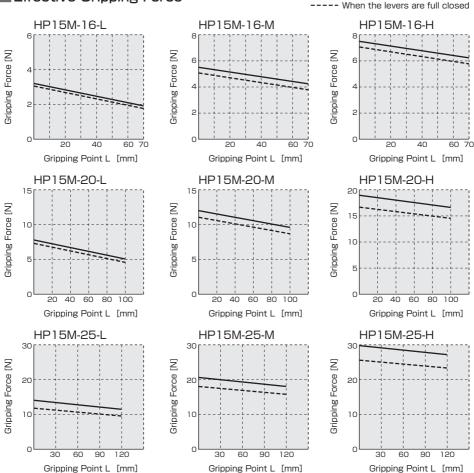
Note 1): Extrusion force is an external force required to open the levers completely by overwhelming the spring force in the closing direction.

Note 2): The lever ratio is the "Extruded Distance (how much the rear rad is extruded) and the "Lever Opening Distance (Lever Opening Distance at that time) (both sides) expressed in "Extruded Distance: Lever Opening Distance".

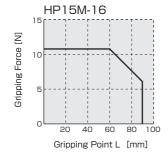
Note 3): The opening/closing stroke is a reference value. Values in the parentheses are measured values.

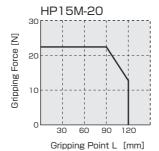
■ Effective Gripping Force

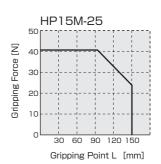
When the levers are full open



■ Gripping Point Limit Range







■ Gripper Attachment Method

Pipe

When you screw in a joint or the like into the pipe port, tighten it with the following torque.

Pipe Port	Maximum Tightening Torque [N·m]		
M3×0.5	0.59		
M5×0.8	1.57		

Attachment Mounting

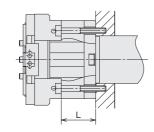
When you mount the attachment, support it with a spanner or the like so that the levers are not rattled. See the following table for the tightening torque of the mounting bolts.

N	lodel	Bolt to be Used	Maximum Tightening Torque [N·m]
HP1	5M-16	M3×0.5	1.14
HP1	5M-20	M4×0.7	2.7
HP1	5M-25	M5×0.8	5.4



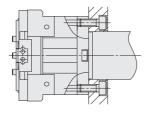
Main Body Mounting Method

1 When the through-hole of the main body is used



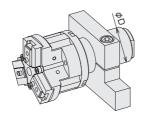
Model	Bolt to be Used	Maximum Tightening Torque [N·m]	L[mm]	
φ16	M3×0.5	0.59	18	
φ20	M3×0.5	0.59	21	
φ25	M4×0.7	1.37	21	

2 When the mounting screw on the back side of the through-hole is used



Model	Bolt to be Used	Maximum Tightening Torque [N·m]		
φ16	M4×0.7	1.37		
φ20	M4×0.7	1.37		
φ25	M5×0.8	2.84		

3 When shank is used

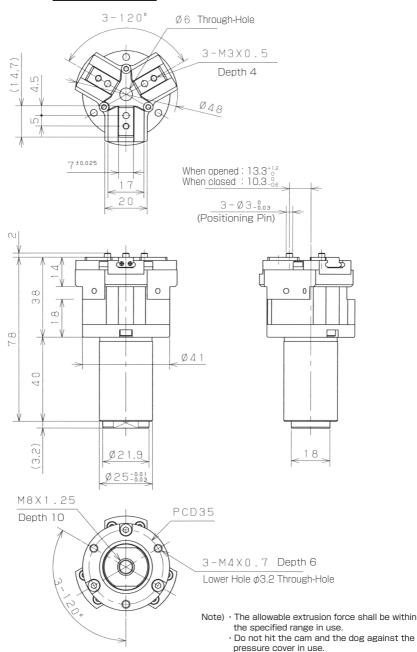


Model	Shank Diameter [ϕ D]
φ16	φ25 ^{-0.01}
φ20	φ30 ^{-0.01}
φ25	φ30 ^{-0.01}

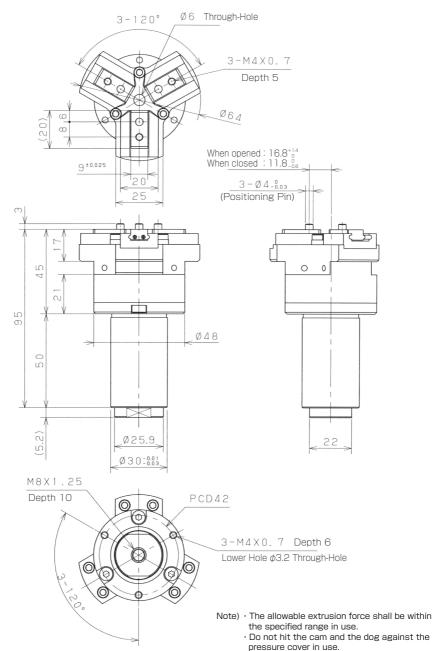
HP15M Series

CAD data provided

■ Dimensions HP15M-16-□



■ Dimensions HP15M-20-□



HP15M Series

CAD data provided

■ Dimensions HP15M-25-

