

# Just like a human hand, gently "hold", "pinch", "pick up"

Robot hand for soft handling

## **SOFTmatics**<sup>™</sup>

Robot hand SOFTmatics™ uses an original gripping mechanism to gently pick up and hold irregularly shaped, mixed, or breakable objects.

About SOFTmatics™

Features

Applications

Specifications • Drawings
• Catalog
Download other
documents

Unable to handle due to variation in size…

### Do you have any of these problems?

Damaging the workpiece…

It is difficult to hold them due to the irregular shape…



Scratching in the pick-and-place ...

We have to do it by hand…

But we can't afford that much manpower…



#### A Gentle Solution to Your Worker Shortage Issue



### Support conveyance automation with SOFTmatics™.

NITTA's "SOFTmatics™" can gently hold, pick up, and pinch the workpiece in place of the human hand for irregular shapes, mixed, or breakable















## More possibilities with customization!

To hold a workpiece without spilling it, to grip a workpiece larger than the gripper, etc.

The shape of the fingers can be changed to match your needs. (The shape below is an example. Please contact us for details.)

